

CFA Identification & Estimation

Theory Construction and Statistical Modeling



**Utrecht
University**

Kyle M. Lang

Department of Methodology & Statistics
Utrecht University

Outline

SAPI Data

Flavors of Latent Construct

- Reflective Constructs

- Formative Constructs

Model Estimation

- Model-Implied Statistics

Model Identification

- Degrees of Freedom

- Just-Identified Models

- Under-Identified Models

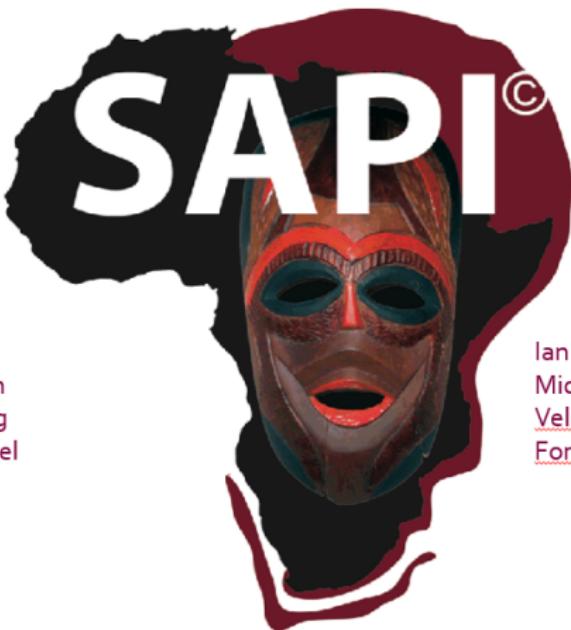
- Over-Identified Models

- Multiple Factors

Example



South African Personality Inventory Project



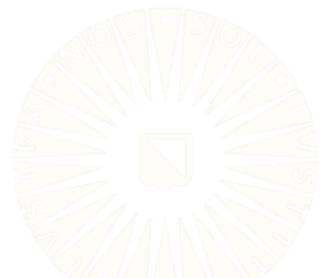
Carin Hill
Leon Jackson
Deon Meiring
J. Aleweyn Nel

Ian Rothmann
Michael Temane
Velichko H. Valchev
Fons J. R. van de Vijver

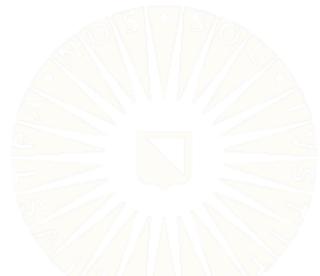
Nel, J. A., Valchev, V. H., Rothmann, S., van de Vijver, F. J. R., Meiring, D., & de Bruin, G. P. (2012). Exploring the personality structure in the 11 languages of South Africa. *Journal of Personality*, 80, 915–948.

SAPI details

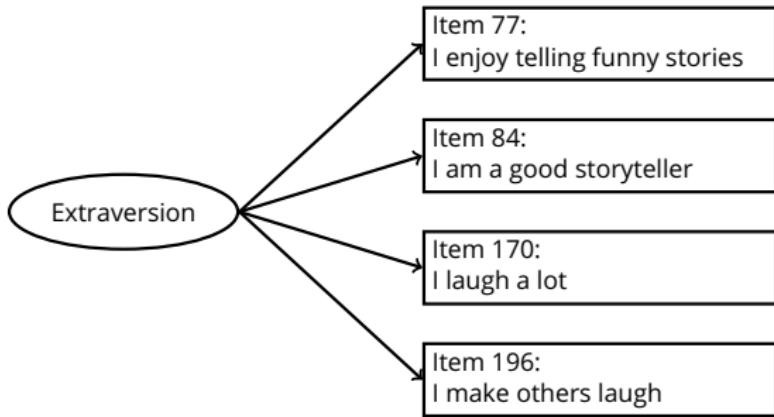
- 1216 participants from 11 official language groups
- From about 50,000 descriptive responses to 262 personality items
- Nine personality clusters:
 - Conscientiousness
 - Emotional Stability
 - Extraversion
 - Facilitating
 - Integrity
 - Intellect
 - Openness
 - Relationship Harmony
 - Soft-Heartedness (Ubuntu)
- Our data: selection of 1000 participants



FLAVORS OF LATENT CONSTRUCT



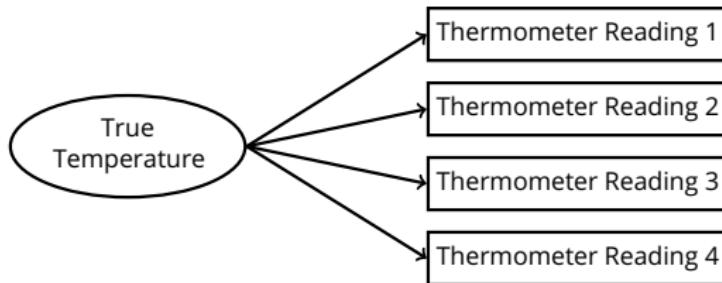
Reflective Constructs



In a reflective measurement model, the items are the dependent variables, and the latent factor is the independent variable.

- The observed items are dependent variables.
- The latent factor is causing the items to take the values we observe.

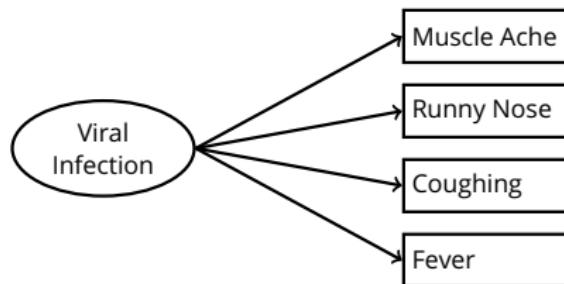
Reflective Constructs



The true temperature is the underlying (unobserved) factor that produces thermometer readings.

- Any given thermometer reading is only an imperfect reflection of the true temperature.
- Multiple readings increase the reliability of our temperature estimate.

Reflective Constructs



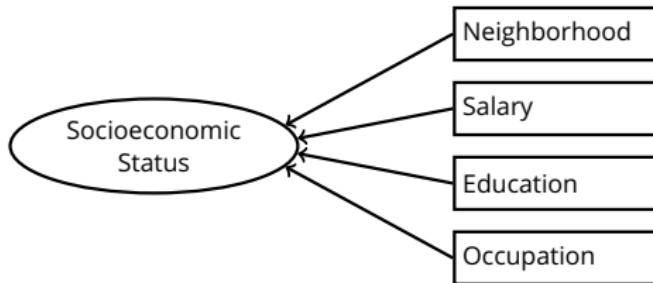
The latent viral infection is the causal factor that gives rise to the observed symptoms of illness.

- Symptoms are the dependent variables.
- Viral infection is the unobserved predictor variable.



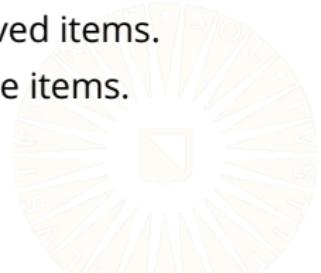
Formative Constructs

Flipping the direction of the factor loadings makes a *formative construct*.

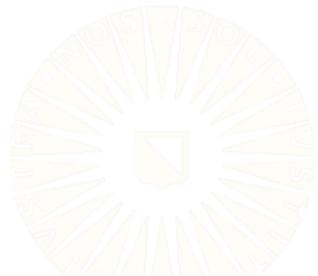


SES is an *index* defined as a (weighted) sum of the observed items.

- SES is the (latent) dependent variable, predicted by the items.
- This model is not empirically testable.



MODEL ESTIMATION



Model-Implied Statistics

Most statistical estimation algorithms operate by minimizing the difference between two key reference points:

1. The *model-implied* statistics/predictions/fitted values

- The sufficient statistics implied by the structure of your model.
- Predicted/fitted values produced by your model.

2. The *observed* statistics/values

- The sufficient statistics calculated from the observed data.
- The raw outcome values from your dataset.

The predictions/implied statistics produced by a good model must be simpler than the analogous quantities in the observed data.

- A model that exactly replicates the observed data is overfitting.
- The inferences from such models won't generalize to the population.

Model-Implied Statistics

You should already be familiar with this idea from OLS regression.

- The fitted values are the model implied statistics.

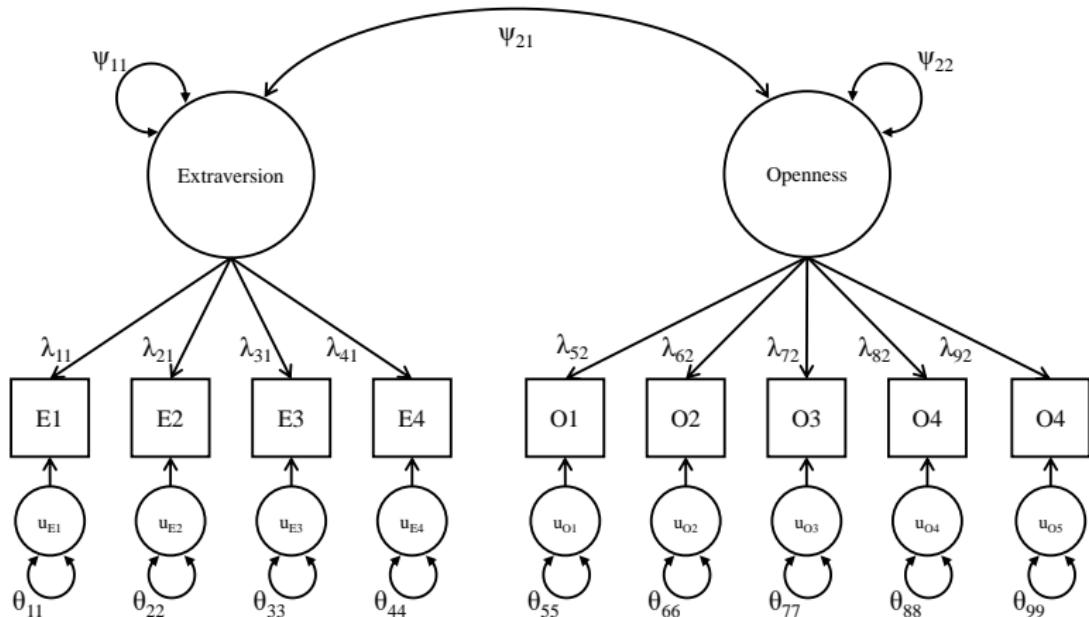
$$\hat{Y}_n = \hat{\beta}_0 + \sum_{p=1}^P \hat{\beta}_p X_{n,p}$$

- The raw outcome variable, Y , contains the observed values.
- Minimize the difference between \hat{Y} and Y to estimate the model.

$$RSS = \sum_{n=1}^N (Y_n - \hat{Y}_n)^2$$



Fully Specified Path Diagram

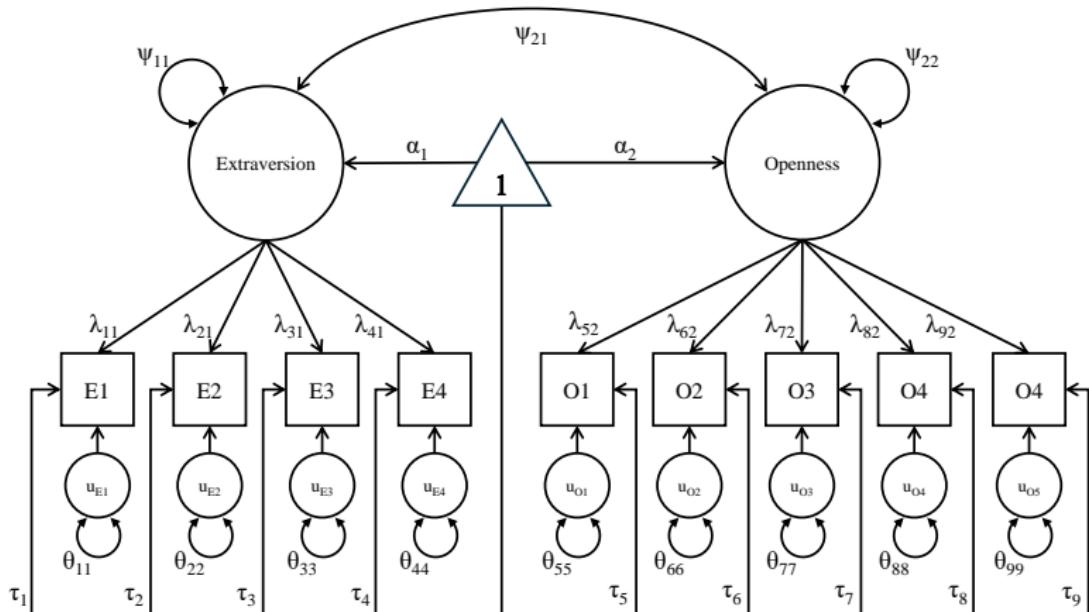


Parameter Matrices

$$\Psi = \begin{bmatrix} \psi_{11} & \\ \psi_{21} & \psi_{22} \end{bmatrix}$$

$$\Theta = \left[\begin{array}{ccccccccc} \theta_{11} & & & & & & & & \\ 0 & \theta_{22} & & & & & & & \\ 0 & 0 & \theta_{33} & & & & & & \\ 0 & 0 & 0 & \theta_{44} & & & & & \\ 0 & 0 & 0 & 0 & \theta_{55} & & & & \\ 0 & 0 & 0 & 0 & 0 & \theta_{66} & & & \\ 0 & 0 & 0 & 0 & 0 & 0 & \theta_{77} & & \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & \theta_{88} & \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \theta_{99} \end{array} \right] \quad \Lambda = \begin{bmatrix} \lambda_{11} & 0 \\ \lambda_{21} & 0 \\ \lambda_{31} & 0 \\ \lambda_{41} & 0 \\ 0 & \lambda_{52} \\ 0 & \lambda_{62} \\ 0 & \lambda_{72} \\ 0 & \lambda_{82} \\ 0 & \lambda_{92} \end{bmatrix}$$

Fully Specified Path Diagram



Parameter Matrices

$$\alpha = \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix} \quad \Psi = \begin{bmatrix} \psi_{11} & \\ \psi_{21} & \psi_{22} \end{bmatrix}$$

$$\tau = \begin{bmatrix} \tau_1 \\ \tau_2 \\ \tau_3 \\ \tau_4 \\ \tau_5 \\ \tau_6 \\ \tau_7 \\ \tau_8 \\ \tau_9 \end{bmatrix} \quad \Theta = \begin{bmatrix} \theta_{11} & & & & & & & & \\ 0 & \theta_{22} & & & & & & & \\ 0 & 0 & \theta_{33} & & & & & & \\ 0 & 0 & 0 & \theta_{44} & & & & & \\ 0 & 0 & 0 & 0 & \theta_{55} & & & & \\ 0 & 0 & 0 & 0 & 0 & \theta_{66} & & & \\ 0 & 0 & 0 & 0 & 0 & 0 & \theta_{77} & & \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & \theta_{88} & \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \theta_{99} \end{bmatrix} \quad \Lambda = \begin{bmatrix} \lambda_{11} & 0 \\ \lambda_{21} & 0 \\ \lambda_{31} & 0 \\ \lambda_{41} & 0 \\ 0 & \lambda_{52} \\ 0 & \lambda_{62} \\ 0 & \lambda_{72} \\ 0 & \lambda_{82} \\ 0 & \lambda_{92} \end{bmatrix}$$

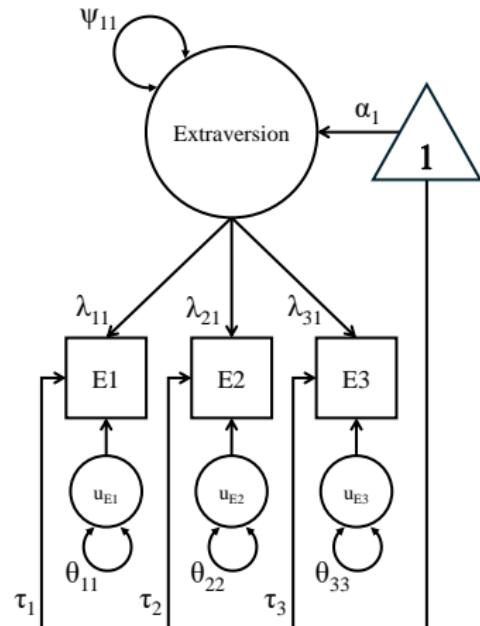
Parameter Matrices

To see what role these parameter matrices play in model estimation, we'll work with a simpler example.

$$\alpha = [\alpha_1] \quad \Psi = [\psi_{11}]$$

$$\tau = \begin{bmatrix} \tau_1 \\ \tau_2 \\ \tau_3 \end{bmatrix} \quad \Lambda = \begin{bmatrix} \lambda_{11} \\ \lambda_{21} \\ \lambda_{31} \end{bmatrix}$$

$$\Theta = \begin{bmatrix} \theta_{11} & & \\ 0 & \theta_{22} & \\ 0 & 0 & \theta_{33} \end{bmatrix}$$



Model-Implied Statistics

The parameter matrices define the model-implied mean vector, $\hat{\mu}$, and covariance matrix, $\hat{\Sigma}$, via the following formulas.

$$\Sigma = \Lambda \Psi \Lambda^T + \Theta$$

$$\mu = \tau + \Lambda \alpha$$

By expanding these formulas, we can see how the model reproduces each mean, variance, and covariance.

$$\hat{\mu} = \begin{bmatrix} \tau_1 + \lambda_{11}\alpha_1 \\ \tau_2 + \lambda_{22}\alpha_1 \\ \tau_3 + \lambda_{33}\alpha_1 \end{bmatrix} \quad \hat{\Sigma} = \begin{bmatrix} \lambda_{11}\psi_{11}\lambda_{11} + \theta_{11} & & \\ \lambda_{11}\psi_{11}\lambda_{21} & \lambda_{21}\psi_{11}\lambda_{21} + \theta_{22} & \\ \lambda_{11}\psi_{11}\lambda_{31} & \lambda_{21}\psi_{11}\lambda_{31} & \lambda_{31}\psi_{11}\lambda_{31} + \theta_{33} \end{bmatrix}$$

Model-Implied Statistics

The estimating algorithm chooses values for α , τ , Ψ , and Λ that minimize the differences between the model-implied statistics, $\{\hat{\mu}, \hat{\Sigma}\}$, and the sufficient statistics calculated from the observed data, $\{\bar{\mathbf{Y}}, \text{Cov}(\mathbf{Y})\}$.

$$\hat{\mu} = \begin{bmatrix} \tau_1 + \lambda_{11}\alpha_1 \\ \tau_2 + \lambda_{22}\alpha_1 \\ \tau_3 + \lambda_{33}\alpha_1 \end{bmatrix} \quad \hat{\Sigma} = \begin{bmatrix} \lambda_{11}\psi_{11}\lambda_{11} + \theta_{11} & & \\ \lambda_{11}\psi_{11}\lambda_{21} & \lambda_{21}\psi_{11}\lambda_{21} + \theta_{22} & \\ \lambda_{11}\psi_{11}\lambda_{31} & \lambda_{21}\psi_{11}\lambda_{31} & \lambda_{31}\psi_{11}\lambda_{31} + \theta_{33} \end{bmatrix}$$

$$\bar{\mathbf{Y}} = \begin{bmatrix} \bar{y}_1 \\ \bar{y}_2 \\ \bar{y}_3 \end{bmatrix} \quad \text{Cov}(\mathbf{Y}) = \begin{bmatrix} var(y_1) & & \\ cov(y_2, y_1) & var(y_2) & \\ cov(y_3, y_1) & cov(y_3, y_2) & var(y_3) \end{bmatrix}$$

Optimization Objective

We can formulate the familiar OLS objective as an abstract optimization problem at follows.

$$f(\beta_0, \beta_1, \dots, \beta_p) = \arg \min_{\beta_0, \beta_1, \dots, \beta_p} \|Y - \hat{Y}\|$$

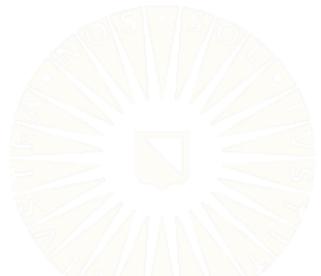
Applying the same idea to our CFA optimization problem, we get the following formulation.

$$f(\Lambda, \Psi) = \arg \min_{\Lambda, \Psi} \|\text{Cov}(Y) - \hat{\Sigma}\|$$

$$f(\tau, \alpha) = \arg \min_{\tau, \alpha} \|\bar{Y} - \hat{\mu}\|$$



MODEL IDENTIFICATION

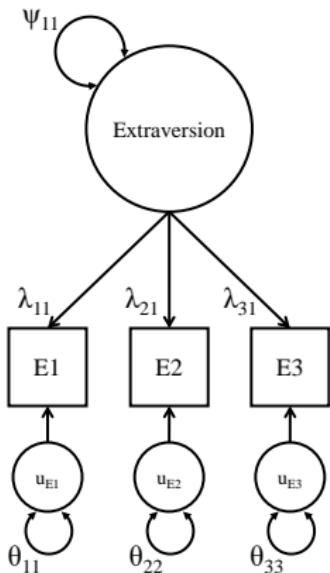


Number of Estimated Parameters

To estimate a CFA model, we must define $\hat{\Sigma}$.

- We must estimate each parameter that defines an element in $\hat{\Sigma}$.
- The constraints on our model determine how many parameter estimates we need.

$$\hat{\Sigma} = \begin{bmatrix} \lambda_{11}\psi_{11}\lambda_{11} + \theta_{11} & & \\ \lambda_{11}\psi_{11}\lambda_{21} & \lambda_{21}\psi_{11}\lambda_{21} + \theta_{22} & \\ \lambda_{11}\psi_{11}\lambda_{31} & \lambda_{21}\psi_{11}\lambda_{31} & \lambda_{31}\psi_{11}\lambda_{31} + \theta_{33} \end{bmatrix}$$

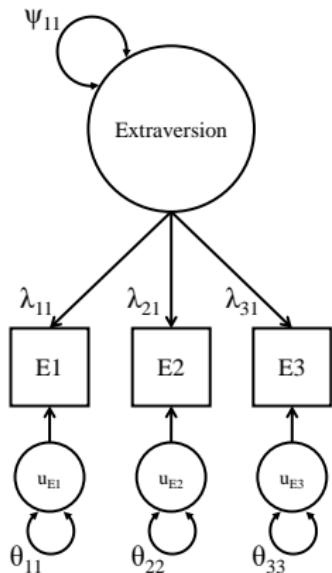


Number of Estimated Parameters

For this example, we need to estimate seven parameters to fully define $\hat{\Sigma}$.

- One latent variance: ψ_{11}
- Three factor loadings: $\{\lambda_{11}, \lambda_{21}, \lambda_{31}\}$
- Three residual variances: $\{\theta_{11}, \theta_{22}, \theta_{33}\}$

$$\hat{\Sigma} = \begin{bmatrix} \lambda_{11}\psi_{11}\lambda_{11} + \theta_{11} & & \\ \lambda_{11}\psi_{11}\lambda_{21} & \lambda_{21}\psi_{11}\lambda_{21} + \theta_{22} & \\ \lambda_{11}\psi_{11}\lambda_{31} & \lambda_{21}\psi_{11}\lambda_{31} & \lambda_{31}\psi_{11}\lambda_{31} + \theta_{33} \end{bmatrix}$$



Available Information

The data only contain a fixed amount of information.

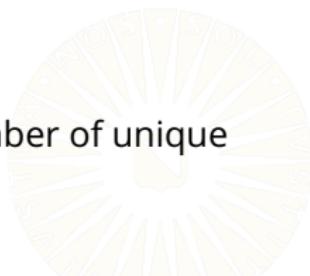
- We can quantify the available information in discrete units.
- Every unique element of $\text{Cov}(\mathbf{Y})$ contributes one unit of information.

$$\text{Cov}(\mathbf{Y}) = \begin{bmatrix} \text{var}(y_1) & & \\ \text{cov}(y_2, y_1) & \text{var}(y_2) & \\ \text{cov}(y_3, y_1) & \text{cov}(y_3, y_2) & \text{var}(y_3) \end{bmatrix}$$

In this example, we have six pieces of available information.

- Three variances: $\text{var}(y_1)$, $\text{var}(y_2)$, $\text{var}(y_3)$
- Three covariances: $\text{cov}(y_2, y_1)$, $\text{cov}(y_3, y_1)$, $\text{cov}(y_3, y_2)$

For a positive-definite $M \times M$ covariance matrix, the number of unique elements will always be $Q = \frac{M(M+1)}{2}$.



Degrees of Freedom

We can only estimate one parameter for each piece of available information, Q .

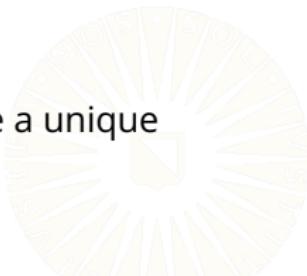
- We can estimate no more than Q parameters in any one model.

The *degrees of freedom* (df) is the difference between the amount of information available in the data, Q , and the number of parameters estimated in our model, P .

$$df = Q - P$$

If $df < 0$, the model is not estimable.

- A model with $df < 0$ is *not identified*.
- The data do not provide enough information to define a unique solution for all P parameter estimates.



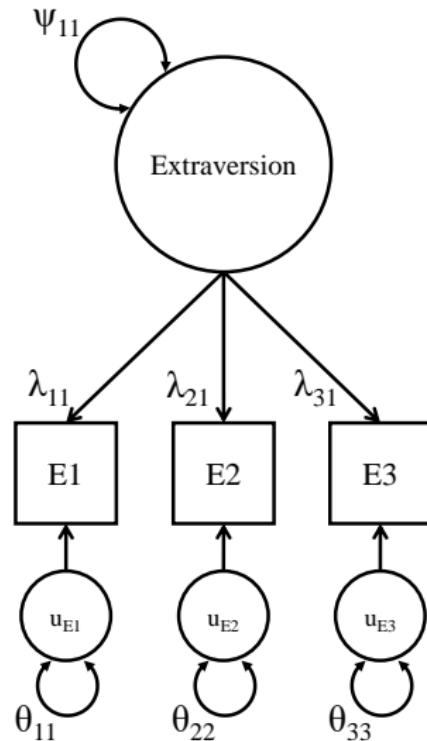
Degrees of Freedom

What are the degrees of freedom for our example?

$$df = Q - P = 6 - 7 = -1$$

This model has negative df .

- We cannot estimate the model in this form.
- We must impose *identifying constraints*.

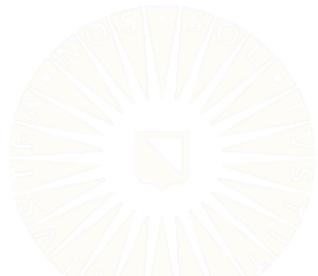


Identifying Constraints

Consider the following equation:

$$5 = x + y$$

What are the values of x and y ?



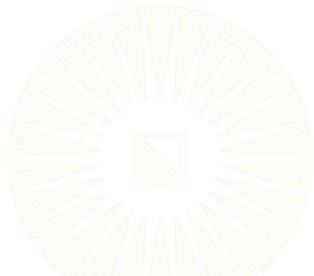
Identifying Constraints

Consider the following equation:

$$5 = x + y$$

What are the values of x and y ?

$$y = 5 - x$$



Identifying Constraints

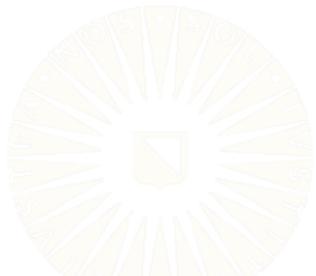
Consider the following equation:

$$5 = x + y$$

What are the values of x and y ?

$$y = 5 - x$$

What if we assume that $y = x$?



Identifying Constraints

Consider the following equation:

$$5 = x + y$$

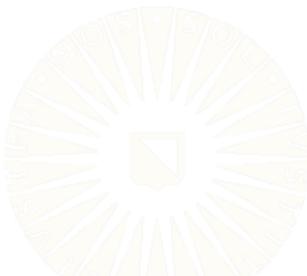
What are the values of x and y ?

$$y = 5 - x$$

What if we assume that $y = x$?

$$5 = x + y$$

$$0 = x - y$$



Identifying Constraints

Consider the following equation:

$$5 = x + y$$

What are the values of x and y ?

$$y = 5 - x$$

What if we assume that $y = x$?

$$5 = x + y$$

$$0 = x - y$$

Now we have enough information:

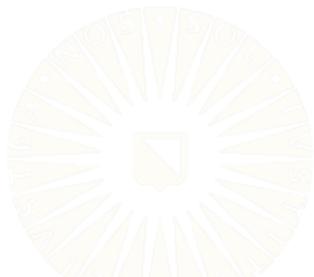
$$5 = x + x = 2x \Rightarrow x = y = 2.5$$



Identifying Constraints

We must fix some parameters to identify the model.

- For each construct, we need $df \geq 0$.
- If the construct has three or more indicators:
 - Fix one parameter in the covariance model.
 - Fix one parameter in the mean model.
- If the construct has two indicators:
 - Fix an additional parameter in the covariance model.
- If the construct has only one indicator:
 - Cannot define a latent factor.



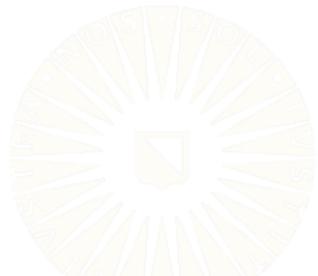
Identifying Constraints

These constraints also define the scale of the latent factors.

- Latent factors have no direct representation as observed variables in our dataset.
- A latent factor only exists after we've estimated it.
- So latent factors have no inherent scale.
- Identifying constraints are also called *scaling constraints*.

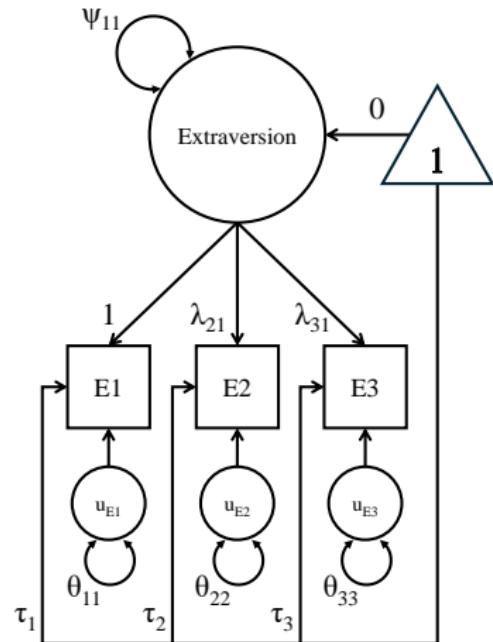
There are two common methods of identifying/scaling CFA models.

1. Marker-variable method
2. Fixed-factor method



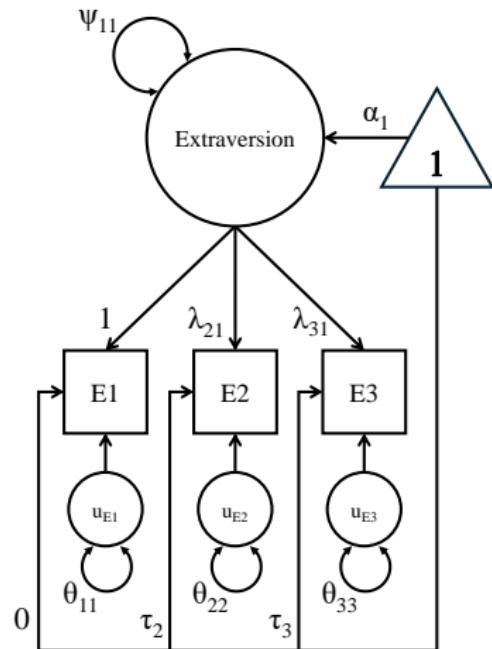
Marker-Variable Method

- Fix one factor loading to 1.
- Fix the latent mean to 0.



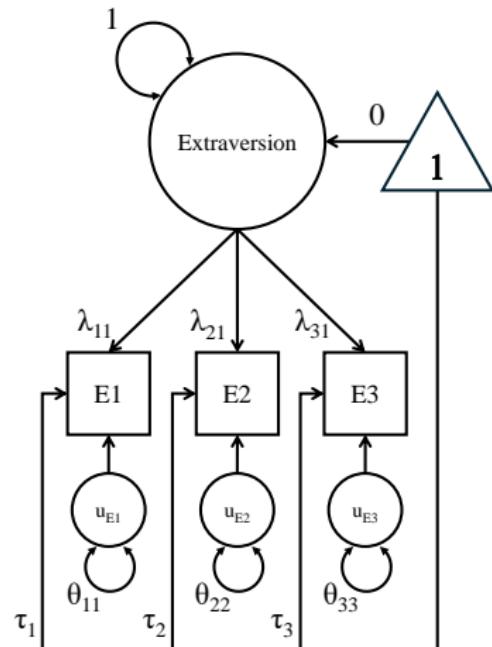
Marker-Variable Method

- Fix one factor loading to 1.
- Estimate the latent mean and fix one item intercept to 0.



Fixed-Factor Method

- Fix the latent variance to 1.
- Fix the latent mean to 0.



Just-Identified: Unconstrained Model

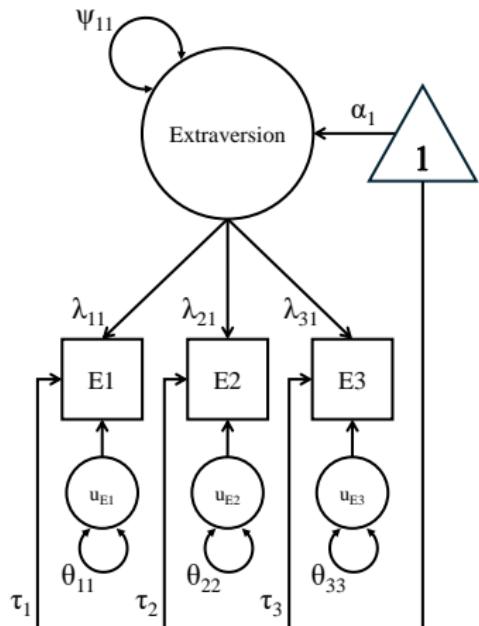
$$\alpha = [\alpha_1] \quad \Psi = [\psi_{11}]$$

$$\tau = \begin{bmatrix} \tau_1 \\ \tau_2 \\ \tau_3 \end{bmatrix} \quad \Lambda = \begin{bmatrix} \lambda_{11} \\ \lambda_{21} \\ \lambda_{31} \end{bmatrix}$$

$$\Theta = \begin{bmatrix} \theta_{11} & & \\ 0 & \theta_{22} & \\ 0 & 0 & \theta_{33} \end{bmatrix}$$

$$Q = \frac{3(3+1)}{2} + 3 = 9$$

$$df = Q - P \\ = 9 - 11 = -2$$



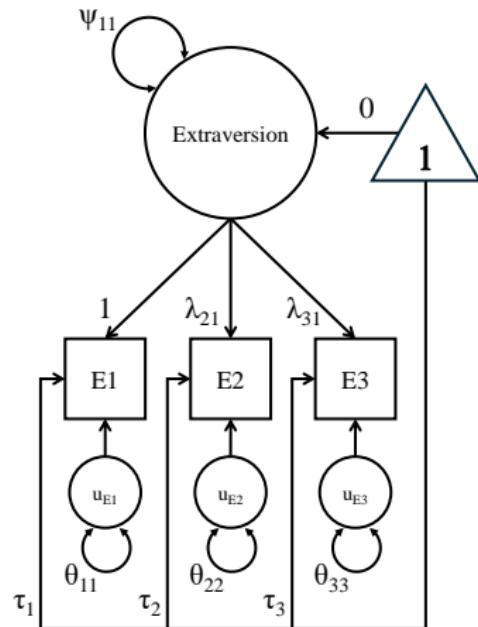
Just-Identified: Marker-Variable

$$\alpha = [0] \quad \Psi = [\psi_{11}]$$

$$\tau = \begin{bmatrix} \tau_1 \\ \tau_2 \\ \tau_3 \end{bmatrix} \quad \Lambda = \begin{bmatrix} 1 \\ \lambda_{21} \\ \lambda_{31} \end{bmatrix}$$

$$\Theta = \begin{bmatrix} \theta_{11} & & \\ 0 & \theta_{22} & \\ 0 & 0 & \theta_{33} \end{bmatrix}$$

$$df = Q - P \\ = 9 - 9 = 0$$



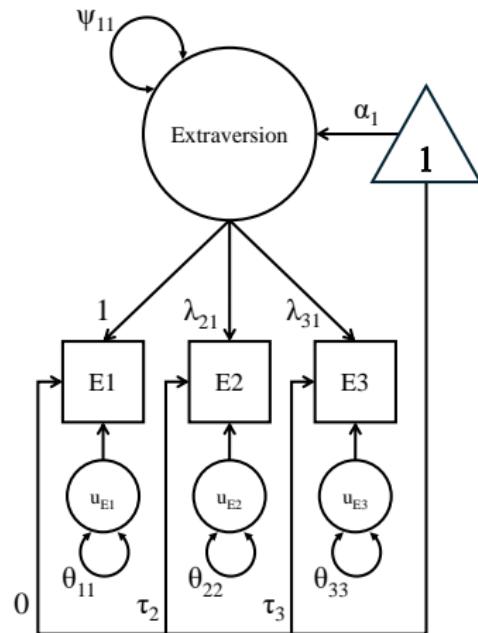
Just-Identified: Marker-Variable

$$\alpha = [\alpha_1] \quad \Psi = [\psi_{11}]$$

$$\tau = \begin{bmatrix} 0 \\ \tau_2 \\ \tau_3 \end{bmatrix} \quad \Lambda = \begin{bmatrix} 1 \\ \lambda_{21} \\ \lambda_{31} \end{bmatrix}$$

$$\Theta = \begin{bmatrix} \theta_{11} & & \\ 0 & \theta_{22} & \\ 0 & 0 & \theta_{33} \end{bmatrix}$$

$$df = Q - P \\ = 9 - 9 = 0$$



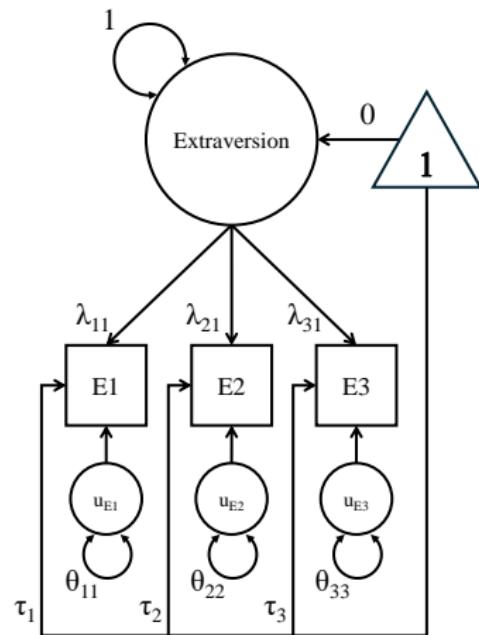
Just-Identified: Fixed-Factor

$$\alpha = [0] \quad \Psi = [1]$$

$$\tau = \begin{bmatrix} \tau_1 \\ \tau_2 \\ \tau_3 \end{bmatrix} \quad \Lambda = \begin{bmatrix} \lambda_{11} \\ \lambda_{21} \\ \lambda_{31} \end{bmatrix}$$

$$\Theta = \begin{bmatrix} \theta_{11} & & \\ 0 & \theta_{22} & \\ 0 & 0 & \theta_{33} \end{bmatrix}$$

$$df = Q - P \\ = 9 - 9 = 0$$



Under-Identified: Unconstrained Model

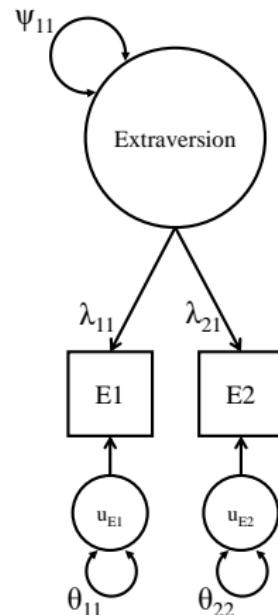
$$\Psi = [\psi_{11}]$$

$$\Lambda = \begin{bmatrix} \lambda_{11} \\ \lambda_{21} \end{bmatrix}$$

$$\Theta = \begin{bmatrix} \theta_{11} & \\ 0 & \theta_{22} \end{bmatrix}$$

$$Q = \frac{2(2+1)}{2} = 3$$

$$\begin{aligned} df &= Q - P \\ &= 3 - 5 = -2 \end{aligned}$$



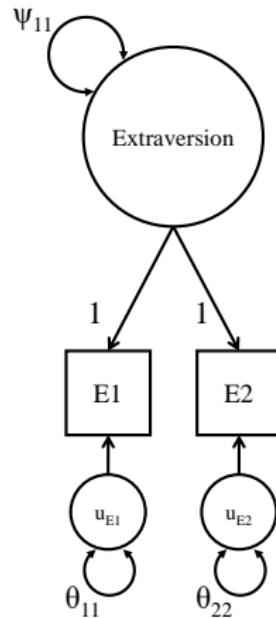
Under-Identified: Marker-Variable

$$\Psi = [\psi_{11}]$$

$$\Lambda = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\Theta = \begin{bmatrix} \theta_{11} & \\ 0 & \theta_{22} \end{bmatrix}$$

$$df = Q - P \\ = 3 - 3 = 0$$



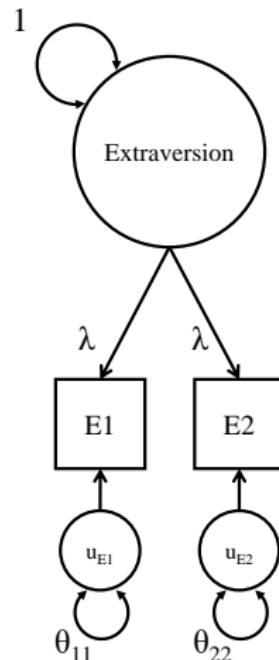
Under-Identified: Fixed-Factor

$$\Psi = [1]$$

$$\Lambda = \begin{bmatrix} \lambda \\ \lambda \end{bmatrix}$$

$$\Theta = \begin{bmatrix} \theta_{11} & \\ 0 & \theta_{22} \end{bmatrix}$$

$$df = Q - P \\ = 3 - 3 = 0$$



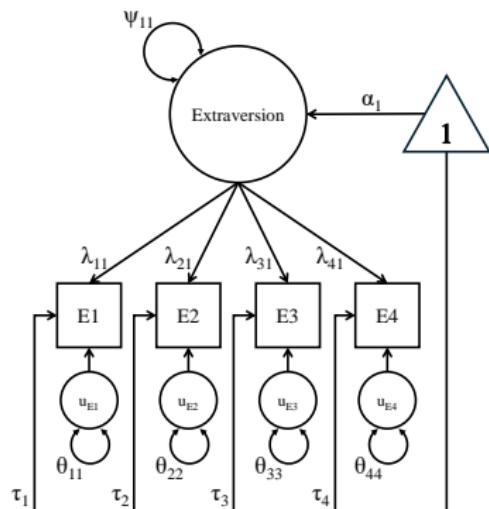
Over-Identified Models

What happens when we have four (or more) indicators?

With 4 indicators, our model contains 14 parameters:

- Four factor loadings
- Four residual variances
- Four item intercepts
- One latent mean
- One latent variance

$$Q = \frac{4(4+1)}{2} + 4 = 14$$
$$df = 14 - 14 = 0$$



Over-Identified Models

With 5 indicators, we have 17 model parameters:

- Five factor loadings
- Five residual variances
- Five item intercepts
- One latent mean
- One latent variance

With 6 indicators, we have 20 model parameters:

- Six factor loadings
- Six residual variances
- Six item intercepts
- One latent mean
- One latent variance

$$Q = \frac{5(5 + 1)}{2} + 5 = 20$$

$$df = 20 - 17 = 3$$

$$Q = \frac{6(6 + 1)}{2} + 6 = 27$$

$$df = 27 - 20 = 7$$

Over-Identified Models

With four indicators, we automatically have $df \geq 0$ without imposing any scaling constraints.

- Can we directly estimate the unconstrained model?

```
mod1 <- '  
fun =~ Q77 + Q84 + Q170 + Q196  
'  
  
fit1 <- lavaan(mod1,  
                 data = sapi,  
                 auto.var = TRUE,  
                 meanstructure = TRUE,  
                 int.ov.free = TRUE,  
                 int.lv.free = TRUE)  
  
Warning: lavaan->lav_model_vcov():  
  Could not compute standard errors! The information matrix could not be  
  inverted. This may be a symptom that the model is not identified.
```

Hmmm...I guess not.

Over-Identified Models

```
partSummary(fit1, 1:4)
```

```
lavaan 0.6-19 ended normally after 13 iterations
```

Estimator	ML
Optimization method	NLMINB
Number of model parameters	14
Number of observations	Used 970 Total 1000
Model Test User Model:	
Test statistic	58.017
Degrees of freedom	0

Over-Identified Models

```
partSummary(fit1, 7:8)
```

Latent Variables:

	Estimate	Std.Err	z-value	P(> z)
fun =~				
Q77	0.824	NA		
Q84	0.578	NA		
Q170	0.479	NA		
Q196	0.619	NA		

Intercepts:

	Estimate	Std.Err	z-value	P(> z)
.Q77	3.574	NA		
.Q84	3.232	NA		
.Q170	3.955	NA		
.Q196	3.803	NA		
fun	0.000	NA		

Over-Identified Models

```
partSummary(fit1, 9)
```

Variances:

	Estimate	Std.Err	z-value	P(> z)
.Q77	0.491	NA		
.Q84	0.760	NA		
.Q170	0.703	NA		
.Q196	0.370	NA		
fun	1.012	NA		

Over-Identified Models

In the above example, the data contain enough information to define our model parameters, but that's not enough.

- We still need scaling constraints.
- The estimation algorithm needs an anchor point from which to extrapolate the relative values of the model parameters.
- Without any scaling constraints, an infinite number of parameter matrices will produce the same $\hat{\mu}$ and $\hat{\Sigma}$.
- An infinite number of solutions are equally good.

```
## Fit a model to get some example parameters:  
mod1 <- '  
  fun   =~ Q77 + Q84 + Q170 + Q196  
  liked =~ Q44 + Q63 + Q76 + Q98  
'  
  
fit1 <- cfa(mod1, data = sapi, effect.coding = TRUE)
```

Over-Identified Models

```
## Extract the estimated factor loadings and latent covariance matrix:  
(lambda <- inspect(fit1, "est")$lambda)  
  
      fun liked  
Q77   1.254 0.000  
Q84   0.954 0.000  
Q170  0.795 0.000  
Q196  0.997 0.000  
Q44   0.000 0.764  
Q63   0.000 1.155  
Q76   0.000 1.133  
Q98   0.000 0.949  
  
(psi <- inspect(fit1, "est")$psi)  
  
      fun liked  
fun    0.399  
liked  0.241 0.311
```

Over-Identified Models

```
## Extract the estimated residual variances:  
(theta <- inspect(fit1, "est")$theta)  
  
          Q77    Q84    Q170   Q196    Q44    Q63    Q76    Q98  
Q77  0.548  
Q84  0.000 0.727  
Q170 0.000 0.000 0.687  
Q196 0.000 0.000 0.000 0.364  
Q44  0.000 0.000 0.000 0.000 0.662  
Q63  0.000 0.000 0.000 0.000 0.000 0.807  
Q76  0.000 0.000 0.000 0.000 0.000 0.000 0.966  
Q98  0.000 0.000 0.000 0.000 0.000 0.000 0.000 0.469
```

Over-Identified Models

```
## Manually compute the model-implied covariance matrix:  
(sigma <- lambda %*% psi %*% t(lambda) + theta)  
  
      Q77   Q84   Q170  Q196   Q44   Q63   Q76   Q98  
Q77  1.176  
Q84  0.477 1.090  
Q170 0.398 0.303 0.940  
Q196 0.499 0.380 0.316 0.761  
Q44  0.231 0.175 0.146 0.183 0.843  
Q63  0.349 0.265 0.221 0.277 0.275 1.223  
Q76  0.342 0.260 0.217 0.272 0.269 0.407 1.365  
Q98  0.287 0.218 0.182 0.228 0.226 0.341 0.335 0.750
```

Over-Identified Models

```
## Randomly sample an arbitrary scaling factor:  
(a <- runif(1, 1, 2))  
  
[1] 1.524314  
  
## Rescale all factor loadings by a factor of a:  
(lambda2 <- lambda * a)  
  
fun liked  
Q77 1.911 0.000  
Q84 1.454 0.000  
Q170 1.212 0.000  
Q196 1.520 0.000  
Q44 0.000 1.164  
Q63 0.000 1.760  
Q76 0.000 1.727  
Q98 0.000 1.447
```

Over-Identified Models

```
## Rescale the latent covariance matrix by a factor of (1 / a^2):
(psi2 <- psi / a^2)

      fun liked
fun   0.172
liked 0.104 0.134

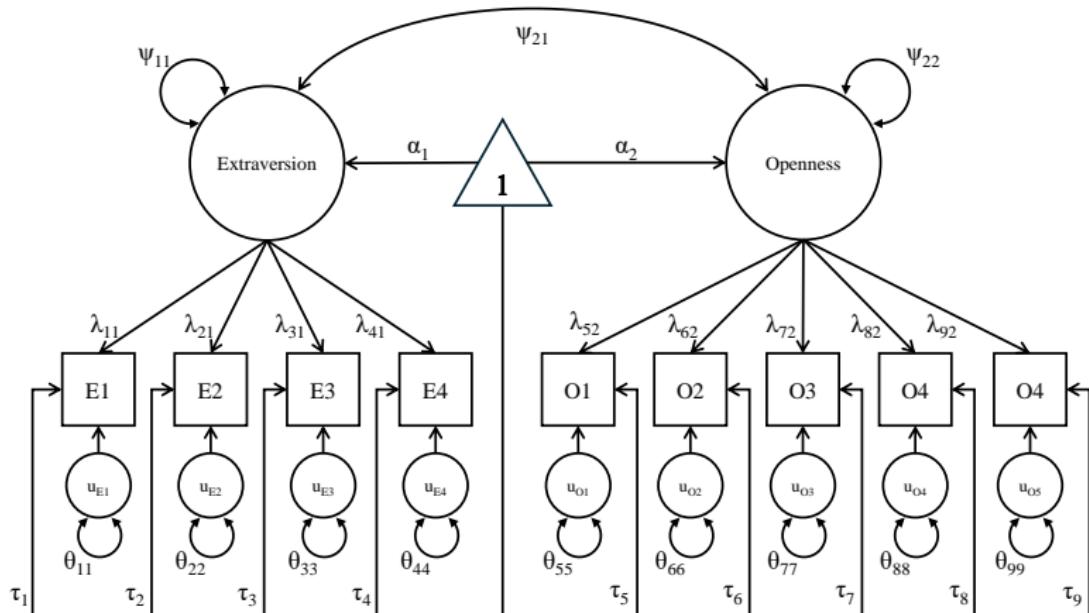
## Compute the model-implied covariance matrix using the rescaled parameters:
(sigma2 <- lambda2 %*% psi2 %*% t(lambda2) + theta)

      Q77   Q84   Q170  Q196   Q44   Q63   Q76   Q98
Q77  1.176
Q84  0.477 1.090
Q170 0.398 0.303 0.940
Q196 0.499 0.380 0.316 0.761
Q44  0.231 0.175 0.146 0.183 0.843
Q63  0.349 0.265 0.221 0.277 0.275 1.223
Q76  0.342 0.260 0.217 0.272 0.269 0.407 1.365
Q98  0.287 0.218 0.182 0.228 0.226 0.341 0.335 0.750
```

Over-Identified Models

```
## Compare the two model-implied covariance matrices:  
all.equal(sigma, sigma2)  
  
[1] TRUE  
  
## Repeat the experiment 100 times:  
out <- rep(NA, 100)  
for(i in 1:100) {  
  a <- runif(1, 1, 2)  
  
  lambda2 <- lambda * a  
  psi2    <- psi / a^2  
  sigma2  <- lambda2 %*% psi2 %*% t(lambda2) + theta  
  
  out[i] <- all.equal(sigma, sigma2)  
}  
  
## Always the same result?  
all(out)  
  
[1] TRUE
```

Two Construct: Unconstrained Model

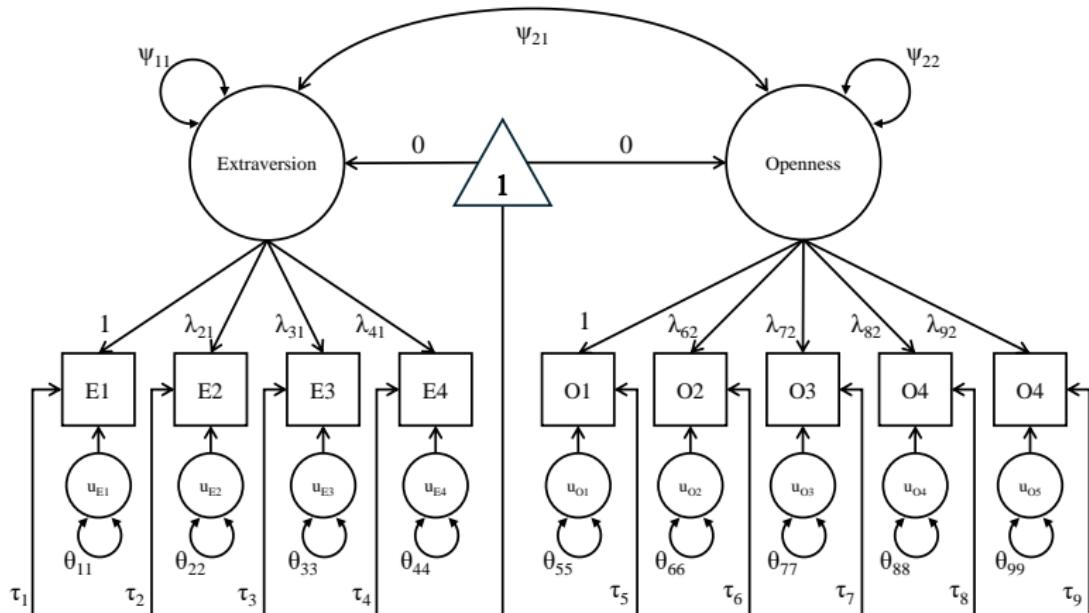


Unconstrained Parameter Matrices

$$\alpha = \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix} \quad \Psi = \begin{bmatrix} \psi_{11} & \\ \psi_{21} & \psi_{22} \end{bmatrix}$$

$$\tau = \begin{bmatrix} \tau_1 \\ \tau_2 \\ \tau_3 \\ \tau_4 \\ \tau_5 \\ \tau_6 \\ \tau_7 \\ \tau_8 \\ \tau_9 \end{bmatrix} \quad \Theta = \begin{bmatrix} \theta_{11} & & & & & & & & \\ 0 & \theta_{22} & & & & & & & \\ 0 & 0 & \theta_{33} & & & & & & \\ 0 & 0 & 0 & \theta_{44} & & & & & \\ 0 & 0 & 0 & 0 & \theta_{55} & & & & \\ 0 & 0 & 0 & 0 & 0 & \theta_{66} & & & \\ 0 & 0 & 0 & 0 & 0 & 0 & \theta_{77} & & \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & \theta_{88} & \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \theta_{99} \end{bmatrix} \quad \Lambda = \begin{bmatrix} \lambda_{11} & 0 \\ \lambda_{21} & 0 \\ \lambda_{31} & 0 \\ \lambda_{41} & 0 \\ 0 & \lambda_{52} \\ 0 & \lambda_{62} \\ 0 & \lambda_{72} \\ 0 & \lambda_{82} \\ 0 & \lambda_{92} \end{bmatrix}$$

Two Construct: Marker variable

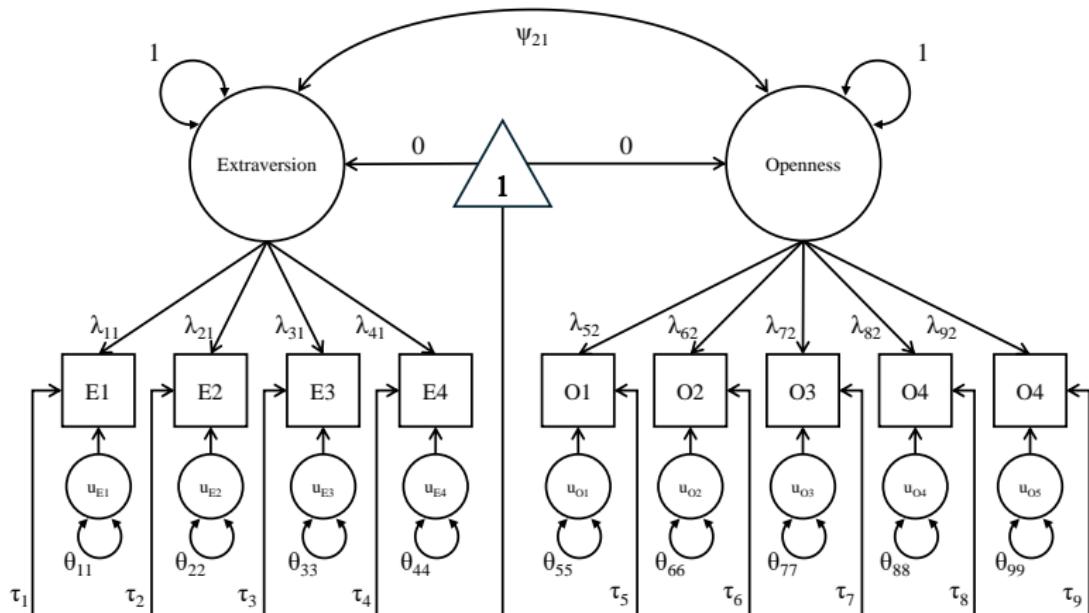


Parameter Matrices: Marker Variable

$$\alpha = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Psi = \begin{bmatrix} \psi_{11} & \\ \psi_{21} & \psi_{22} \end{bmatrix}$$

$$\tau = \begin{bmatrix} \tau_1 \\ \tau_2 \\ \tau_3 \\ \tau_4 \\ \tau_5 \\ \tau_6 \\ \tau_7 \\ \tau_8 \\ \tau_9 \end{bmatrix} \quad \Theta = \begin{bmatrix} \theta_{11} & & & & & & & & \\ 0 & \theta_{22} & & & & & & & \\ 0 & 0 & \theta_{33} & & & & & & \\ 0 & 0 & 0 & \theta_{44} & & & & & \\ 0 & 0 & 0 & 0 & \theta_{55} & & & & \\ 0 & 0 & 0 & 0 & 0 & \theta_{66} & & & \\ 0 & 0 & 0 & 0 & 0 & 0 & \theta_{77} & & \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & \theta_{88} & \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \theta_{99} \end{bmatrix} \quad \Lambda = \begin{bmatrix} 1 & 0 \\ \lambda_{21} & 0 \\ \lambda_{31} & 0 \\ \lambda_{41} & 0 \\ 0 & 1 \\ 0 & \lambda_{62} \\ 0 & \lambda_{72} \\ 0 & \lambda_{82} \\ 0 & \lambda_{92} \end{bmatrix}$$

Two Construct: Fixed-Factor

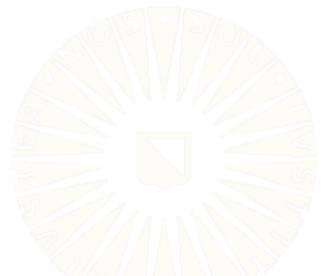


Parameter Matrices: Fixed-Factor

$$\alpha = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \Psi = \begin{bmatrix} 1 & \\ \psi_{21} & 1 \end{bmatrix}$$

$$\tau = \begin{bmatrix} \tau_1 \\ \tau_2 \\ \tau_3 \\ \tau_4 \\ \tau_5 \\ \tau_6 \\ \tau_7 \\ \tau_8 \\ \tau_9 \end{bmatrix} \quad \Theta = \begin{bmatrix} \theta_{11} & & & & & & & & \\ 0 & \theta_{22} & & & & & & & \\ 0 & 0 & \theta_{33} & & & & & & \\ 0 & 0 & 0 & \theta_{44} & & & & & \\ 0 & 0 & 0 & 0 & \theta_{55} & & & & \\ 0 & 0 & 0 & 0 & 0 & \theta_{66} & & & \\ 0 & 0 & 0 & 0 & 0 & 0 & \theta_{77} & & \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & \theta_{88} & \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \theta_{99} \end{bmatrix} \quad \Lambda = \begin{bmatrix} \lambda_{11} & 0 \\ \lambda_{21} & 0 \\ \lambda_{31} & 0 \\ \lambda_{41} & 0 \\ 0 & \lambda_{52} \\ 0 & \lambda_{62} \\ 0 & \lambda_{72} \\ 0 & \lambda_{82} \\ 0 & \lambda_{92} \end{bmatrix}$$

EXAMPLE



CFA of Extraversion Items

Suppose we hypothesize two distinct dimensions of extraversion underlying 8 of the SAPI items.

1. Having Fun
2. Being Liked by Others

We'll define our measurement model as the two-factor CFA shown to the right.



Example: Marker Variable

Load the SAPI data.

```
dataDir <- "../data/"  
sapi <- read.table(paste0(dataDir, "sapi.txt"),  
                    header = TRUE,  
                    na.strings = "-999")
```

Specify the **lavaan** model syntax for the SAPI extraversion CFA.

```
mod1 <- '  
fun    =~ Q77 + Q84 + Q170 + Q196  
liked =~ Q44 + Q63 + Q76 + Q98  
'
```

Use the `cfa()` function to estimate the model.

```
library(lavaan)  
out1 <- cfa(mod1, data = sapi)
```

Example: Marker Variable

```
partSummary(out1, 1:4)
```

lavaan 0.6-19 ended normally after 30 iterations

Estimator	ML
Optimization method	NLMINB
Number of model parameters	17
Number of observations	Used 959
	Total 1000

Model Test User Model:

Test statistic	130.193
Degrees of freedom	19
P-value (Chi-square)	0.000

Example: Marker Variable

```
partSummary(out1, 5:7)
```

Parameter Estimates:

Standard errors	Standard
Information	Expected
Information saturated (h1) model	Structured

Latent Variables:

	Estimate	Std.Err	z-value	P(> z)
fun =~				
Q77	1.000			
Q84	0.761	0.051	14.902	0.000
Q170	0.634	0.047	13.558	0.000
Q196	0.795	0.046	17.381	0.000
liked =~				
Q44	1.000			
Q63	1.512	0.147	10.278	0.000
Q76	1.483	0.149	9.955	0.000
Q98	1.243	0.119	10.462	0.000

Example: Marker Variable

```
partSummary(out1, 8:9)
```

Covariances:

	Estimate	Std.Err	z-value	P(> z)
fun ~~				
liked	0.231	0.025	9.234	0.000

Variances:

	Estimate	Std.Err	z-value	P(> z)
.Q77	0.548	0.038	14.389	0.000
.Q84	0.727	0.039	18.703	0.000
.Q170	0.687	0.035	19.572	0.000
.Q196	0.364	0.025	14.731	0.000
.Q44	0.662	0.034	19.291	0.000
.Q63	0.807	0.048	16.943	0.000
.Q76	0.966	0.054	17.931	0.000
.Q98	0.469	0.029	16.121	0.000
fun	0.627	0.056	11.303	0.000
liked	0.182	0.029	6.290	0.000

Example: Marker Variable

```
inspect(out1, "r2")  
  
Q77   Q84   Q170  Q196   Q44   Q63   Q76   Q98  
0.534 0.333 0.268 0.521 0.215 0.340 0.293 0.374  
  
fitMeasures(out1) |> head(22) |> round(3)  
  
      npar          fmin          chisq          df  
    17.000        0.068       130.193     19.000  
      pvalue    baseline.chisq  baseline.df  baseline.pvalue  
    0.000        1574.886      28.000      0.000  
      cfi            tli          nnfi          rfi  
    0.928        0.894        0.894      0.878  
      nfi            pnfi          ifi          rni  
    0.917        0.622        0.929      0.928  
      logl  unrestricted.logl          aic          bic  
 -10147.587      -10082.491      20329.175    20411.895  
      ntotal          bic2  
  959.000        20357.903
```

Example: Marker Variable

```
fitMeasures(out1) |> tail(-22) |> round(3)
```

	rmsea	rmsea.ci.lower	rmsea.ci.upper
	0.078	0.066	0.091
	rmsea.ci.level	rmsea.pvalue	rmsea.close.h0
	0.900	0.000	0.050
rmsea.notclose.pvalue	rmsea.notclose.h0	rmr	
	0.421	0.080	0.042
	rmr_nomean	srmr	srmr_bentler
	0.042	0.043	0.043
srmr_bentler_nomean		crmr	crmr_nomean
	0.043	0.049	0.049
srmr_mplus	srmr_mplus_nomean		cn_05
	0.043	0.043	223.037
	cn_01	gfi	agfi
	267.582	0.968	0.939
	pgfi	mfi	ecvi
	0.511	0.944	0.171

Example: Fixed Factor

We only need to change one option to implement the fixed-factor method.

- The `std.lv = TRUE` option (i.e., standardized latent variables) applies the appropriate constraints.

```
out2 <- cfa(mod1, data = sapi, std.lv = TRUE)
```

Example: Fixed Factor

```
partSummary(out2, 1:4)
```

```
lavaan 0.6-19 ended normally after 17 iterations
```

Estimator	ML
Optimization method	NLMINB
Number of model parameters	17
	Used Total
Number of observations	959 1000

Model Test User Model:

Test statistic	130.193
Degrees of freedom	19
P-value (Chi-square)	0.000

Example: Fixed Factor

```
partSummary(out2, 5:7)
```

Parameter Estimates:

Standard errors	Standard
Information	Expected
Information saturated (h1) model	Structured

Latent Variables:

	Estimate	Std.Err	z-value	P(> z)
fun =~				
Q77	0.792	0.035	22.606	0.000
Q84	0.603	0.035	17.193	0.000
Q170	0.502	0.033	15.180	0.000
Q196	0.630	0.028	22.308	0.000
liked =~				
Q44	0.426	0.034	12.580	0.000
Q63	0.644	0.040	16.071	0.000
Q76	0.632	0.043	14.845	0.000
Q98	0.530	0.031	16.912	0.000

Example: Fixed Factor

```
partSummary(out2, 8:9)
```

Covariances:

	Estimate	Std.Err	z-value	P(> z)
fun ~~				
liked	0.683	0.033	20.483	0.000

Variances:

	Estimate	Std.Err	z-value	P(> z)
.Q77	0.548	0.038	14.389	0.000
.Q84	0.727	0.039	18.703	0.000
.Q170	0.687	0.035	19.572	0.000
.Q196	0.364	0.025	14.731	0.000
.Q44	0.662	0.034	19.291	0.000
.Q63	0.807	0.048	16.943	0.000
.Q76	0.966	0.054	17.931	0.000
.Q98	0.469	0.029	16.121	0.000
fun	1.000			
liked	1.000			

Example: Fixed Factor

```
inspect(out2, "r2")
```

```
Q77   Q84   Q170  Q196   Q44   Q63   Q76   Q98  
0.534 0.333 0.268 0.521 0.215 0.340 0.293 0.374
```

```
fitMeasures(out2) |> head(22) |> round(3)
```

	npar	fmin	chisq	df
	17.000	0.068	130.193	19.000
pvalue	baseline.chisq	baseline.df	baseline.pvalue	
	0.000	1574.886	28.000	0.000
cfi	tli	nnfi	rfi	
	0.928	0.894	0.894	0.878
nfi	pnfi	ifi	rni	
	0.917	0.622	0.929	0.928
logl	unrestricted.logl	aic	bic	
-10147.587	-10082.491	20329.175	20411.895	
ntotal	bic2			
959.000	20357.903			

Example: Fixed Factor

```
fitMeasures(out2) |> tail(-22) |> round(3)
```

rmsea	rmsea.ci.lower	rmsea.ci.upper
0.078	0.066	0.091
rmsea.ci.level	rmsea.pvalue	rmsea.close.h0
0.900	0.000	0.050
rmsea.notclose.pvalue	rmsea.notclose.h0	rmr
0.421	0.080	0.042
rmr_nomean	srmr	srmr_bentler
0.042	0.043	0.043
srmr_bentler_nomean	crmr	crmr_nomean
0.043	0.049	0.049
srmr_mplus	srmr_mplus_nomean	cn_05
0.043	0.043	223.037
cn_01	gfi	agfi
267.582	0.968	0.939
pgfi	mfi	ecvi
0.511	0.944	0.171

Compare Results

```
inspect(out1, "est")$lambda - inspect(out2, "est")$lambda
```

```
    fun liked
Q77  0.208 0.000
Q84  0.158 0.000
Q170 0.132 0.000
Q196 0.165 0.000
Q44  0.000 0.574
Q63  0.000 0.868
Q76  0.000 0.851
Q98  0.000 0.713
```

```
inspect(out1, "est")$psi - inspect(out2, "est")$psi
```

```
    fun  liked
fun   -0.373
liked -0.453 -0.818
```

Compare Results

```
all.equal(fitMeasures(out1), fitMeasures(out2))

[1] TRUE

inspect(out1, "r2") - inspect(out2, "r2")

Q77  Q84  Q170 Q196  Q44  Q63  Q76  Q98
  0    0    0    0    0    0    0    0

inspect(out1, "est")$theta - inspect(out2, "est")$theta

      Q77  Q84  Q170 Q196  Q44  Q63  Q76  Q98
Q77    0
Q84    0    0
Q170   0    0    0
Q196   0    0    0    0
Q44    0    0    0    0    0
Q63    0    0    0    0    0    0
Q76    0    0    0    0    0    0    0
Q98    0    0    0    0    0    0    0    0
```